

Wigner-Eckart

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↓ Zare/Edmonds

$$\langle n_1 j_1 m_1 | \hat{T}_M^{(J)} | n_2 j_2 m_2 \rangle \equiv (-1)^{2J} \frac{\langle n_1 j_1 || \hat{T}^{(J)} || n_2 j_2 \rangle}{[j_1]^{1/2}} \langle j_1 m_1 J M | j_2 m_2 \rangle \quad [1]$$

$$= (-1)^{j_1 - m_1} \begin{pmatrix} j_1 & J & j_2 \\ -m_1 & M & m_2 \end{pmatrix} \langle n_1 j_1 || \hat{T}^{(J)} || n_2 j_2 \rangle \quad [2]$$

$$\hat{T}_{m, m_2}^{(J)}(j_1, j_2) \equiv |j_1 m_1\rangle \langle j_2 m_2| \quad [3]$$

$$\hat{T}_{KQ}^{(J)}(j_1, j_2) \equiv \sum_{m_1 m_2} \hat{T}_{m_1 m_2}^{(J)}(j_1, j_2) (-1)^{2K + j_2 - m_2} \langle j_1 m_1 j_2 -m_2 | KQ \rangle \quad [4]$$

$$= \sum_{m_1 m_2} \hat{T}_{m_1 m_2}^{(J)}(j_1, j_2) (-1)^{j_1 - m_1} [K]^{1/2} \begin{pmatrix} j_1 & K & j_2 \\ -m_1 & Q & m_2 \end{pmatrix} \quad [5]$$

$$\hat{T}_M^{(J)} = \sum_{n_1 n_2 j_1 j_2 m_1 m_2} |n_1 j_1 m_1\rangle \langle n_1 j_1 m_1 | \hat{T}_M^{(J)} | n_2 j_2 m_2 \rangle \langle n_2 j_2 m_2| \quad [6]$$

$$\hat{T}_M^{(J)} = \sum_{j_1 j_2} \hat{T}_M^{(J)}(j_1, j_2) \sum_{n_1 n_2} |n_1\rangle \langle n_1 j_1 || \hat{T}^{(J)} || n_2 j_2 \rangle \langle n_2| \quad [7]$$

$$\hat{T}_{K_1 Q_1}^{(J)}(j_1, j_2) \hat{T}_{K_2 Q_2}^{(J)}(j_2, j_3) = \sum_{K_3 Q_3} \hat{T}_{K_3 Q_3}^{(J)}(j_1, j_3) [K_1]^{1/2} [K_2]^{1/2} (-1)^{j_1 + j_2 + K_3} \quad [8]$$

$$\times \left\{ \begin{matrix} j_1 & j_2 & K_1 \\ K_2 & K_3 & j_3 \end{matrix} \right\} \langle K_1 Q_1 K_2 Q_2 | K_3 Q_3 \rangle \quad [9]$$

$$\hat{T}_{K_1 Q_1}^{(J)}(j_1, j_2) \hat{T}_{K_2 Q_2}^{(J)}(j_2, j_3) \hat{T}_{K_3 Q_3}^{(J)}(j_3, j_4) = \sum_{K_4 Q_4} \hat{T}_{K_4 Q_4}^{(J)}(j_1, j_4) [K_1]^{1/2} [K_2]^{1/2} [K_3]^{1/2} [K_4]^{1/2} \quad [10]$$

$$\times (-1)^{-j_2 + j_4 + K_2 + K_3 + Q_2} \sum_j [J] \left\{ \begin{matrix} j_1 & j_2 & K_1 \\ j_4 & j_3 & K_3 \\ K_4 & K_2 & j \end{matrix} \right\} \begin{pmatrix} K_1 & j & K_3 \\ Q_1 & m & Q_3 \end{pmatrix} \begin{pmatrix} K_2 & j & K_4 \\ Q_2 & -m & -Q_4 \end{pmatrix}$$

$$(m = Q_1 + Q_3)$$

$$\hat{T}_{K_1 Q_1}^{(J)}(j_1, j_2) \hat{T}_{K_2 Q_2}^{(J)}(j_2, j_3) \hat{T}_{K_3 Q_3}^{(J)}(j_3, j_4) \hat{T}_{K_4 Q_4}^{(J)}(j_4, j_5) = \sum_{K_5 Q_5} \hat{T}_{K_5 Q_5}^{(J)}(j_1, j_5) [K_1]^{1/2} [K_2]^{1/2} [K_3]^{1/2} [K_4]^{1/2} [K_5]^{1/2} \quad [11]$$

$$\times (-1)^{-j_2 - j_5 + j_6 + K_1 - K_2 + K_3} \sum_{j_6 j_7} [j_6] [j_7] \left\{ \begin{matrix} j_1 & j_2 & K_1 \\ j_5 & j_4 & K_4 \\ K_5 & j_7 & j_6 \end{matrix} \right\} \left\{ \begin{matrix} j_2 & j_3 & K_2 \\ K_3 & j_7 & j_4 \end{matrix} \right\}$$

$$\times \begin{pmatrix} K_1 & K_4 & j_6 \\ Q_1 & Q_4 & m_6 \end{pmatrix} \begin{pmatrix} K_2 & K_3 & j_7 \\ Q_2 & Q_3 & m_7 \end{pmatrix} \begin{pmatrix} j_6 & j_7 & K_5 \\ m_6 & m_7 & Q_5 \end{pmatrix}$$

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Special cases of

$$[\hat{T}_{K_1}(j_1 j_2) \otimes \hat{T}_{K_2}(j_3 j_4)]_{Q_3}^{(K_3)} = \sum_{\gamma_1 \gamma_2} \hat{T}_{K_3 Q_3}[(j_1 j_2) \gamma_1; (j_3 j_4) \gamma_2] \left\{ \begin{matrix} j_1 j_2 K_1 \\ j_3 j_4 K_2 \\ \gamma_1 \gamma_2 K_3 \end{matrix} \right\} [\gamma_1]^{1/2} [\gamma_2]^{1/2} [K_3]^{1/2}$$

③ $K_3 = 0 \Rightarrow K_1 = K_2; \gamma_1 = \gamma_2$

$$\left\{ \begin{matrix} j_1 j_2 K_1 \\ j_3 j_4 K_1 \\ \gamma_1 \gamma_1 0 \end{matrix} \right\} = \frac{(-1)^{j_2 + K_1 + j_3 + \gamma_1}}{[K_1]^{1/2} [\gamma_1]^{1/2}} \left\{ \begin{matrix} j_1 j_2 K_1 \\ j_4 j_3 \gamma_1 \end{matrix} \right\}$$

$$[\hat{T}_{K_1}(j_1 j_2) \otimes \hat{T}_{K_1}(j_3 j_4)]_0^{(0)} = \sum_{\gamma_1} \hat{T}_{00}[(j_1 j_2) \gamma_1; (j_3 j_4) \gamma_1] \left\{ \begin{matrix} j_1 j_2 K_1 \\ j_4 j_3 \gamma_1 \end{matrix} \right\} [\gamma_1]^{1/2} [K_1]^{1/2} (-1)^{j_2 + j_3 + K_1 + \gamma_1}$$

① $K_1 = 0 \Rightarrow j_1 = j_2; K_2 = K_3; Q_3 = Q_2$ $\langle 00 K_2 Q_2 | K_3 Q_3 \rangle = \delta_{K_1 K_2} \delta_{Q_1 Q_3}$

$$\left\{ \begin{matrix} j_1 j_2 0 \\ j_3 j_4 K_2 \\ \gamma_1 \gamma_2 K_2 \end{matrix} \right\} = \frac{(-1)^{\gamma_1 + K_2 + j_4 + j_1}}{[K_2]^{1/2} [\gamma_1]^{1/2}} \left\{ \begin{matrix} \gamma_2 \gamma_1 K_2 \\ j_3 j_4 j_1 \end{matrix} \right\}$$

$$[j_1]^{1/2} \hat{T}_{00}(j_1 j_2) \otimes \hat{T}_{K_2 Q_2}(j_3 j_4) = \sum_{\gamma_1 \gamma_2} \hat{T}_{K_2 Q_2}[(j_1 j_2) \gamma_1; (j_3 j_4) \gamma_2] \left\{ \begin{matrix} \gamma_2 \gamma_1 K_2 \\ j_3 j_4 j_1 \end{matrix} \right\} [\gamma_1]^{1/2} [\gamma_2]^{1/2} [K_2]^{1/2} (-1)^{j_1 + j_4 + K_2 + \gamma_1} \times (-1)$$

$K_2 = 0 \Rightarrow j_3 = j_4; K_3 = K_1$

$$\left\{ \begin{matrix} j_1 j_2 K_1 \\ j_3 j_3 0 \\ \gamma_1 \gamma_2 K_1 \end{matrix} \right\} = \frac{(-1)^{j_1 + K_1 + \gamma_2 + j_3}}{[K_1]^{1/2} [\gamma_2]^{1/2}} \left\{ \begin{matrix} j_2 j_1 K_1 \\ \gamma_1 \gamma_2 j_3 \end{matrix} \right\}$$

$$\hat{T}_{K_1 Q_1}(j_1 j_2) \otimes \hat{T}_{00}(j_3 j_3) [j_3]^{1/2} = \sum_{\gamma_1 \gamma_2} \hat{T}_{K_1 Q_1}[(j_1 j_2) \gamma_1; (j_3 j_3) \gamma_2] \left\{ \begin{matrix} j_2 j_1 K_1 \\ \gamma_1 \gamma_2 j_3 \end{matrix} \right\} [\gamma_1]^{1/2} [\gamma_2]^{1/2}$$

$$[j_1]^{1/2} \hat{T}_{0,0}(j_1 j_1) \otimes [j_2]^{1/2} \hat{T}_{0,0}(j_2 j_2) = \sum_{\gamma} [\gamma]^{1/2} \hat{T}_{0,0}[(j_1 j_1) \gamma; (j_2 j_2) \gamma] \times (-1)^{j_1 + j_2 + K_1 + \gamma_2}$$

$$\hat{F} = \sum_j [j]^{1/2} \hat{T}_{00}(j, j) \quad \left[\text{Note: un-polarized state } \hat{\rho} = [j]^{-1/2} \hat{T}_{00}(j, j) \right]$$

B.F.

$$\hat{T}_{K, Q_1}(j_1 j_2) \otimes \hat{F} = \sum_{\gamma_2 Q_2 Q_3} \hat{T}_{K, Q_1}[j_1 Q_2 \gamma_1; j_2 Q_2 \gamma_2] [\gamma_1]^{1/2} [\gamma_2]^{1/2} \begin{pmatrix} j_1 K_1 j_2 \\ \bar{Q}_1 Q_2 Q_3 \end{pmatrix} \begin{pmatrix} \gamma_1 K_1 \gamma_2 \\ \bar{Q}_1 Q_2 Q_3 \end{pmatrix}$$

$Q \equiv Q_1, -Q_2$

$$\hat{A}_{K, Q_1}^{SF} = \sum_{j_1 j_2} \hat{T}_{K, Q_1}(j_1 j_2) \alpha(j_1 j_2)$$

$$= \sum_{\gamma_1 \gamma_2 j_1 j_2 Q_2 Q_3} \hat{T}_{K, Q_1}[j_1 Q_2 \gamma_1; j_2 Q_2 \gamma_2] \langle j_1 Q_1 | \hat{A}_{K, Q_1}^{SF} | j_2 Q_2 \rangle \begin{pmatrix} \gamma_1 K_1 \gamma_2 \\ \bar{Q}_1 Q_2 Q_3 \end{pmatrix} \frac{[\gamma_1]^{1/2} [\gamma_2]^{1/2}}{[K_1]^{1/2}}$$

Alternative

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$$\hat{T}_{K_1 Q_1}(j_1 j_2) \hat{T}_{K_2 Q_2}(j_2 j_3) \hat{T}_{K_3 Q_3}(j_3 j_4) \hat{T}_{K_4 Q_4}(j_4 j_5)$$

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$$= \sum_{K_A Q_A} \hat{T}_{K_A Q_A}(j_1 j_3) [K_1]^{1/2} [K_2]^{1/2} (-1)^{j_1 + j_3 + K_A} \left\{ \begin{matrix} j_1 j_2 K_1 \\ K_2 K_A j_3 \end{matrix} \right\} \langle K_1 Q_1 K_2 Q_2 | K_A Q_A \rangle$$

$$\sum_{K_B Q_B} \hat{T}_{K_B Q_B}(j_3 j_5) [K_3]^{1/2} [K_4]^{1/2} (-1)^{j_3 + j_5 + K_B} \left\{ \begin{matrix} j_3 j_4 K_3 \\ K_4 K_B j_5 \end{matrix} \right\} \langle K_3 Q_3 K_4 Q_4 | K_B Q_B \rangle$$

$$= \sum_{K_Q} \hat{T}_{K_Q}(j_1 j_5) [K_1]^{1/2} [K_2]^{1/2} [K_3]^{1/2} [K_4]^{1/2} [K_A]^{1/2} [K_B]^{1/2}$$

$$(K_A K_B) (-1)^{j_1 + j_3 + K_A + j_3 + j_5 + K_B + j_1 + j_5 + K}$$

$$\left\{ \begin{matrix} j_1 j_2 K_1 \\ K_2 K_A j_3 \end{matrix} \right\} \left\{ \begin{matrix} j_3 j_4 K_3 \\ K_4 K_B j_5 \end{matrix} \right\} \left\{ \begin{matrix} j_1 j_3 K_A \\ K_B K j_5 \end{matrix} \right\}$$

$$\langle K_1 Q_1 K_2 Q_2 | K_A Q_A \rangle \langle K_3 Q_3 K_4 Q_4 | K_B Q_B \rangle \langle K_A Q_A K_B Q_B | K_Q$$

$$\text{phase } (-1)^{2j_1 + 2j_3 + 2j_5 + K_A + K_B + K}$$

$$\hat{T}_{KQ}^{\dagger}(j_1 j_2) = (-1)^{j_2 - j_1 + Q} \hat{T}_{K, -Q}(j_2 j_1)$$

$$T_{K, Q_1}(j, i) = \sum_{m, m_1} |j, m\rangle \langle i, m_1| \langle j, m, i, m_1 | K, Q_1 \rangle (-1)^{2K_1}$$

$$T_{K_2, Q_2}(j_2, i_2) = \sum_{m_2, m_1} |j_2, m_2\rangle \langle i_2, m_1| \langle j_2, m_2, i_2, m_1 | K_2, Q_2 \rangle (-1)^{2K_2}$$

$$|(j, i_2) T_1, M_1\rangle = \sum_{m_1, m_2} |j, m_1\rangle |j_2, m_2\rangle \langle j, m_1, j_2, m_2 | T_1, M_1\rangle$$

$$|(j_2, i_2) T_2, M_2\rangle = \sum_{m_2, m_3} |j_2, m_2\rangle |i_2, m_3\rangle \langle j_2, m_2, i_2, m_3 | T_2, M_2\rangle$$

$$\hat{T}_{K_3, Q_3}[(j, i_2) T_1; (j_2, i_2) T_2] = \sum_{M_1, M_2} |(j, i_2) T_1, M_1\rangle \langle (j_2, i_2) T_2, M_2| \langle T_1, M_1, T_2, M_2 | K_3, Q_3 \rangle (-1)^{2K_3}$$

$$\hat{T}_{K_1, Q_1}(j, i) \otimes \hat{T}_{K_2, Q_2}(j_2, i_2) = \sum_{T_1, Q_1, T_2, Q_2} \hat{T}_{K_3, Q_3}[(j, i_2) T_1; (j_2, i_2) T_2] \langle K_3, Q_3 | (j, i, j_2, i_2) \rangle$$

$$\langle K_3, Q_3 | (j, i_2) T_1; (j_2, i_2) T_2 \rangle = \{ \hat{T}_{K_3, Q_3}^\dagger[(j, i_2) T_1; (j_2, i_2) T_2] [\hat{T}_{K_1, Q_1}(j, i) \otimes \hat{T}_{K_2, Q_2}(j_2, i_2)] \}$$

$$= \left\{ \begin{matrix} j, i, K_1 \\ j_2, i_2, K_2 \\ T_1, T_2, K_3 \end{matrix} \right\} \langle K_1, Q_1, K_2, Q_2 | K_3, Q_3 \rangle [T_1]^{1/2} [T_2]^{1/2} [K_1]^{1/2} [K_2]^{1/2}$$

$$[\hat{T}_{K_1, Q_1}(j, i) \otimes \hat{T}_{K_2, Q_2}(j_2, i_2)]_{Q_3}^{(K_3)} = \sum_{T_1, T_2} \hat{T}_{K_3, Q_3}[(j, i_2) T_1; (j_2, i_2) T_2] \left\{ \begin{matrix} j, i, K_1 \\ j_2, i_2, K_2 \\ T_1, T_2, K_3 \end{matrix} \right\} [T_1]^{1/2} [T_2]^{1/2} [K_1]^{1/2} [K_2]^{1/2}$$

[B&L 3.24d]

[B&S 5.12]

$$|j, \bar{m}\rangle = (-1)^{j-m} |j, m\rangle$$

$$\langle j_1, m_1, j_2, m_2 | j_3, m_3 \rangle = (-1)^{j_1 - j_2 + j_3} \left(\begin{matrix} j_1, j_2, j_3 \\ m_1, m_2, m_3 \end{matrix} \right) [j_3]^{1/2}$$

$$\left(\begin{matrix} j_1, j_2, j_3 \\ m_1, m_2, m_3 \end{matrix} \right) = (-1)^{2j_3} \left(\begin{matrix} j_1, j_2, j_3 \\ \bar{m}_1, \bar{m}_2, m_3 \end{matrix} \right)$$

$$\begin{array}{c} j_1 \quad j_2 \quad j_3 \\ \swarrow \quad \downarrow \quad \searrow \\ + \quad + \quad + \\ \swarrow \quad \downarrow \quad \searrow \\ j_1 \quad j_2 \quad j_3 \end{array} = \begin{array}{c} j_1 \quad j_2 \quad j_3 \\ \swarrow \quad \downarrow \quad \searrow \\ + \quad + \quad + \\ \swarrow \quad \downarrow \quad \searrow \\ j_1 \quad j_2 \quad j_3 \end{array} = (-1)^{2j_3} \begin{array}{c} j_1 \quad j_2 \quad j_3 \\ \swarrow \quad \downarrow \quad \searrow \\ + \quad + \quad + \\ \swarrow \quad \downarrow \quad \searrow \\ j_1 \quad j_2 \quad j_3 \end{array}$$

$$\begin{aligned} \hat{T}_{J_2}(j, i) &= \sum_{m, m_1} |j, m\rangle \langle i, m_1| \langle j, m, i, m_1 | J_2 \rangle (-1)^{2J_1} \\ &= \sum_{m, m_1} |j, m\rangle \langle i, m_1| \langle j, m, i, m_1 | J_2 \rangle (-1)^{j_1 - m_1 + 2J_2} \\ &= \sum_{m, m_1} |j, m\rangle \langle i, m_1| \left(\begin{matrix} j_1, J_2, j_2 \\ -m_1, 2, m_1 \end{matrix} \right) (-1)^{j_1 - m_1} [J_2]^{1/2} \\ &= \sum_{m, m_1} |j, m\rangle \langle i, m_1| \langle j_2, m_2 | J_2 | j_1, m_1 \rangle (-1)^{2J_2} \end{aligned}$$